



Exp. Date: 4-30-10

# Engineering Study

for the proposed

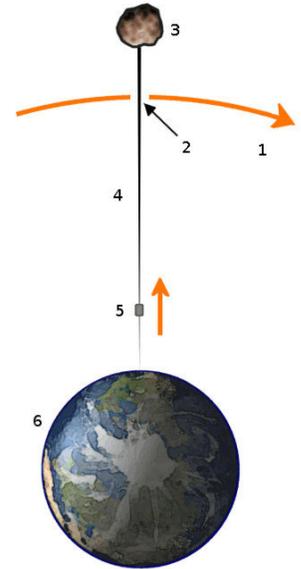
# HCG Space Elevator

September 9, 2009

## A. Background

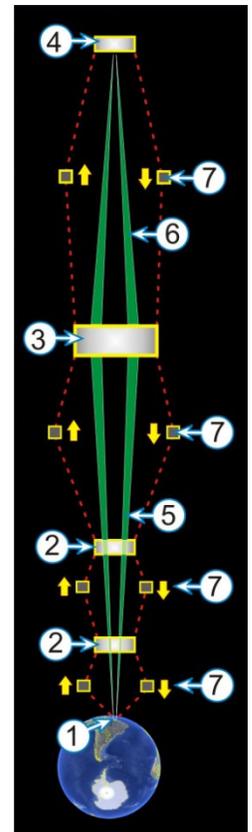
We are not alone. There are other life forms and civilizations out there. We need to go out and meet *them there* before *they* meet us *here*. And there are many other doomsday scenarios: asteroids, gamma ray bursts, black holes, super-novas, killer viruses and bacteria, nuclear war, Sky-Net and mad scientists. As long as we all live here on this one planet, we as a species are at risk of extinction. *We must colonize other worlds to ensure our survival.*

“A **space elevator** is a method for lifting objects into Earth orbit much less expensively than chemical rockets. It has a lower cable (4) anchored to the Earth's surface (6) extending into space. It uses a counterweight (3) 60,000 miles up to keep the cable stretched tightly (like a yo-yo). An elevator cab (5) rides up the cable to reach geostationary orbit (2) at 22,000 miles. (From Wikipedia....*Diagram not to scale.*)”



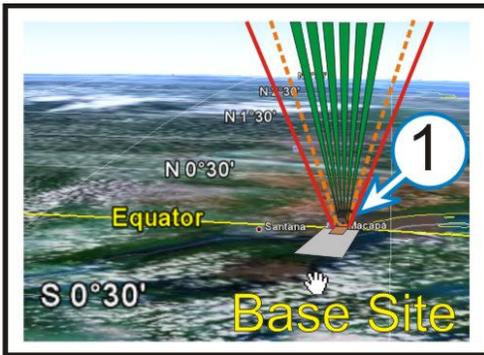
The construction of a space elevator is beyond our current technology. The cables required to build it can't be made yet. The weight of a 60,000 mile cable will snap any known existing material. But there are promising materials (i.e. carbon nanotubes) that might work.

This study examines the engineering aspects of a possible space elevator, including the materials, forces, cable stresses, maintenance issues, safety concerns, costs, and the future technology required to build one. The proposed *HCG Space Elevator* is shown at right.



- 1) It has a **Base Station**;
- 2) Two **Transfer Stations**: at 2,000 & 5,000 miles;
- 3) A **GS Platform** in Geostationary Orbit;
- 4) A **Counterweight**;
- 5) **Tapered Support Cables** connecting the Base, Transfer Stations, and GS Platform;
- 6) **Tapered Support Cables** connecting the Platform to the Counterweight;
- 7) Four sets of **elevator cabs**.

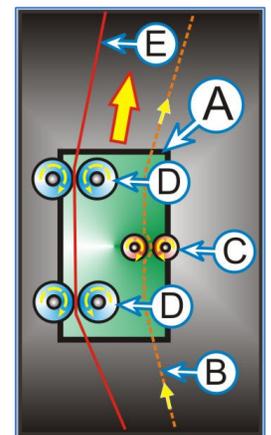
**B. Major Components**



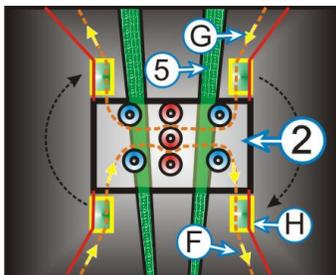
The **Base Station** (1) is in the town of Makapa, Brazil: 2009 Population 330,000. It lies on Brazil’s east coast, on the equator, and on the Amazon River. This provides excellent transportation and infrastructure support.

All system power is generated down here and transmitted to the elevator cabs and platforms thru Drive Ribbons. Local energy sources include river and ocean currents (using HCG’s HeliTubes of course), wind energy (HeliWinds), BioMass, and solar (CSC I’s).

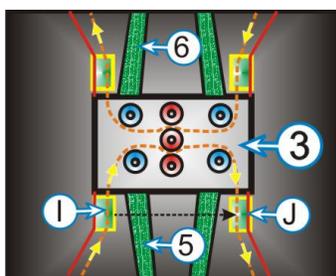
The 20,000 pound **Elevator Cabs** (A) carry 20,000 pounds of cargo and passengers up to the platforms. The **Drive Ribbon** (B) is powered from the Base Station at 10 mph, turning the **Genset** (C), which energizes the **Drive Wheels** (D). This moves the cab up (or down) the **Climbing Ribbon** (E). For safety, there are four drive and four climbing ribbons for each cab.



The torque between the Drive and Climbing Ribbons delivers 55,000 pounds of thrust to the Genset (C). 85% of this power is sent on to the drive wheels, and the remaining 15% powers the cab, provides a 0.2 g cab acceleration, or is lost to friction and heat. The kinetic energy is converted into potential energy as the cab rises. The cabs move at 50 mph in atmosphere but once in space, the cab weight progressively decreases (i.e. it’s zero pounds at the GS Platform) and a top speed of 2,000 mph is possible. Bends in the ribbons are due to coriolis forces as the cabs accelerate and decelerate horizontally going into and leaving orbit.



**Transfer Station # 1** (2) is at 2,000 miles. The **Lower Support Cables** (5) attach the Station to the GS Platform above. This is a good place for inserting payloads into low earth orbit. The Lower Drive Ribbon (F) cycles through the Station, providing Station power and also powering the Upper Drive Ribbon (G). During the layover, the Cabs (H) are switched between the upper and lower elevator ribbons. **Transfer Station # 2** is at 5,000 miles.

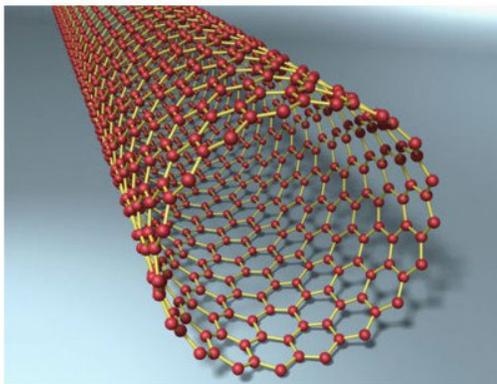


The **GS Platform** (3) is in Geostationary Orbit (22,240 miles), held there by the **Upper Support Cables** (6). The Cabs (H) dock here to transfer crew and cargo. In general, the down cab weighs less than the up cab. The drive ribbon powers the upper cabs and a Genset to power the Platform. The Upper Support Cables attaches to the **Counterweight** (4) at 60,000 miles. After docking, the cabs are moved from the up to the down tethers for the return trip (I ==> J). For safety, the Support Cables are divided into sixteen separated groups.

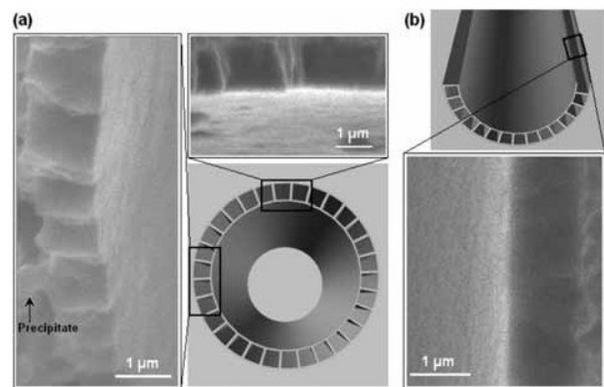
**C. Tether**

The materials we currently have are not strong enough to build the tethers. Pull the strongest steel cable off the surface of the earth and it will snap just 16 miles up. Kevlar can be pulled 160 miles up before it snaps. The highest strength-to-weight ratio materials we have now are just too weak to work. But one promising material may eventually work: the **carbon nanotube (CNT)**. It is pure carbon, formed by rolling up a flat sheet of graphite into a cylinder. The hexagonal crystal lattice employs the strongest chemical bond we know of: the  $sp^2$  carbon bond. Its diameter is usually 1.5 microns. Theoretically, a carbon nanotube can stretch hundreds of thousands of miles into space without breaking. But not yet. So far, we can't make it in lengths longer than 0.001", and we can't role it into threads much stronger than Kevlar.

A new form of CNT, the **colossal carbon nanotube (CCNT)**, is even more promising. Although it is not stronger than CNTs, its lower density provides a higher strength to weight ratio. It is the only potential material we have, so far, that could work. Maybe. It is usually 84 microns across, with the cell columns (basically single wall CNTs) 1.4 microns across.

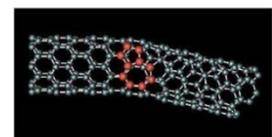


**Carbon Nanotube**

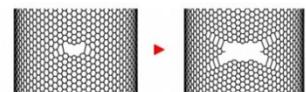


**Colossal Carbon Nanotube**

Theoretically, filaments of carbon nanotubes can resist tensile stresses of 43.5 Million psi (300 GPa) before they break. In comparison, our strongest steels fail at 0.40 M psi. But in practice, so far, CNTs can only reach 1 million psi due to lattice defects. These include the *Stone Walls* defect, where the regular hexagonal crystal structure is replaced by pentagonal and heptagonal arrangements. *Lattice ripping* also restricts ultimate loading of CNT Filaments. The CCNT appears to be much tougher than a single wall CNT and is expected to significantly reduce the weakening caused by these defects.



Stone Walls



Lattice Ripping

CNT's are highly corrosive. They oxidize in the atmosphere, breaking down the crystalline structure. In space, they're exposed to intense ultraviolet light from the sun and high energy cosmic rays. They will be impacted by micrometeorites and space debris. The useful life of a CCNT tether needs to be assessed. A test panel of carbon nanotubes needs to be installed on the *International Space Station* to learn the effects of long-term space exposure on CCNT's. A realistic budget for the Space Elevator depends on knowing how often to replace the tethers.

An individual CCNT filament is about the width of a human hair and, so far, can only be produced in lengths of a few millimeters. When rolled into threads, the filaments bond poorly, and 98% of the inherent strength of the CCNT is lost. Eventually, a method for the continuous extrusion of CCNTs must be found. Then the filaments can be wound into threads, the threads wound into tendons, and the tendons woven into cables and ribbons.

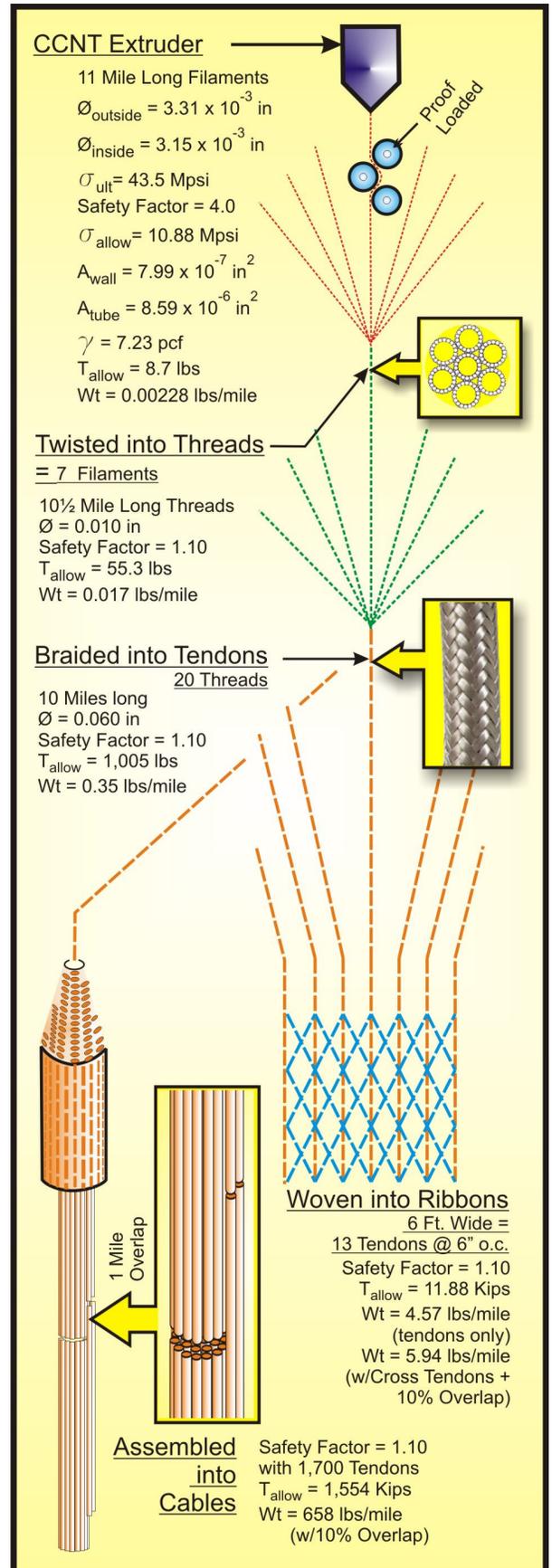
The properties of the CCNT filament presented in this report are based on the '08 work by Huisheng Peng:

- Ultimate Stress = 300 GPa = 43.5 M psi
- Safety Factor = 4.0
- Design Stress = 10.88 M psi
- Density =  $0.116 \text{ gm/cm}^3 = 7.23 \text{ pcf}$

A *Continuos CCNT Extruder* is shown at right (hopefully developed by H. Peng by 2015, with a stress capacity of 25% of the theoretical ultimate stress?). An 11 mile long filament could be produced in four years at an extrusion rate of 1.66 ft/hour or 0.0055"/second. A single *Peng CCNT Filament* is expected to safely support 8.7 pounds. A proof-load roller must test filament strength before further fabrication.

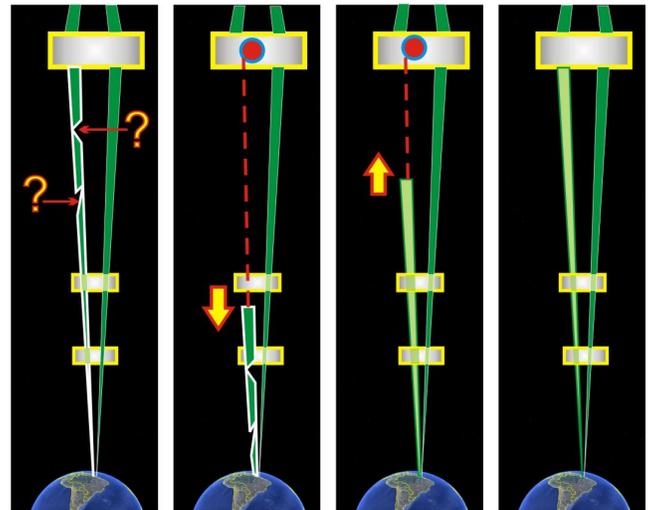
Ten and a half mile long **Threads** are made by twisting seven 11 mile long Filaments together. Estimated allowable thread capacity is 55.3 pounds. Similarly, 10 mile long **Tendons** are made by braiding twenty 10 mile long Threads together. Tendon diameter is 0.060" and allowable loading is estimated at 1,005 pounds.

The Tendons are woven into **Elevator Drive Ribbons**. With tendons 6" on center, a six foot wide Ribbon has 13 tendons and can support a 11,880 pound load. To make a continuous Ribbon Loop, 10 mile long Ribbon segments are overlapped 1 mile to allow *Van der Waals* force to develop the full tendon capacity.

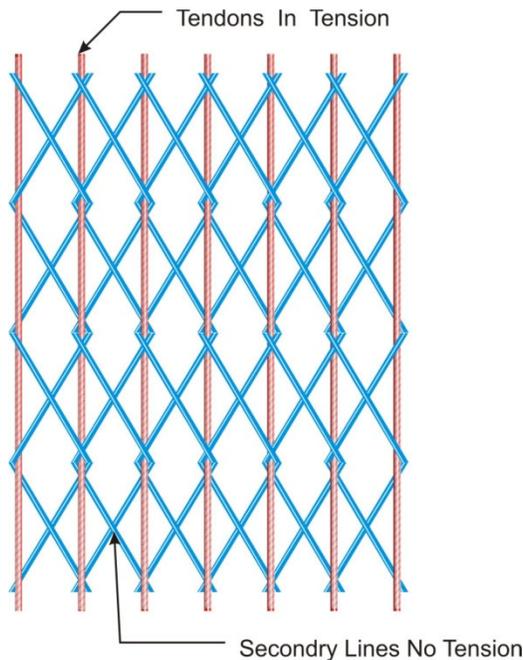


The Support Cables are tapered since even a uniform CNNT cable or ribbon cannot be lifted from the ground into GS orbit without snapping. By tapering the section, the net weight is reduced and the Elevator is structurally possible.

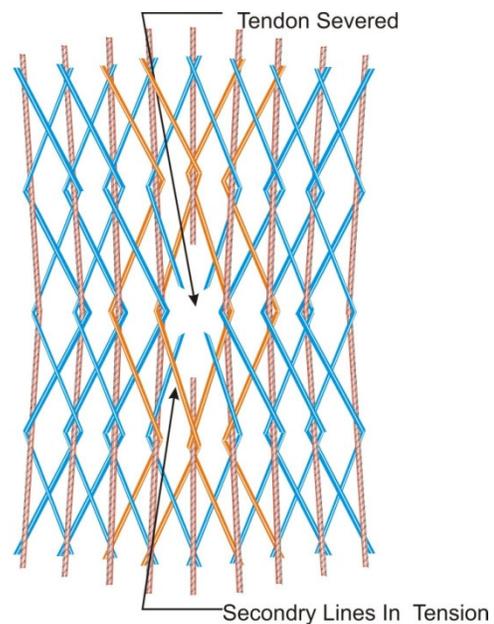
The support cables are made from thousands of tendons layered together with one mile overlaps. These support tethers are separated into 16 groups so that an impact with a space object will hopefully only sever one cable group. This study allows one of the Support Cables to be severed and a second to be out of service for repair. To repair a damaged Support Cable, the bad cable is detached, lowered to the ground, a new cable hoisted back up to the Platform, reattached, and put back into service (see at right).



A Drive Ribbon is woven from tendons spaced 6” apart. Spacing the tendons at 6” reduces the damage effects caused by impacts from small space debris and micro-meteorites. Even so, every ribbon will degrade in the space environment and a safety factor of 1.1 is assigned for the ribbon’s design capacity. Ribbons are necessary to provide traction for the elevator drive wheels. (Gripping a round CCNT cable is nearly impossible.) Severing of a drive ribbon tendon is inevitable. To reduce the effect of this failure, a **Hoytfabric Ribbon** is proposed:



**Hoytfabric Ribbon**



**Ruptured Hoytfabric**

Primary tendons (shown in red) are 0.060" diameter and spaced 6" apart. When first installed, they carry all the tension loads. Secondary lines (shown in blue) are 0.020" in diameter and to keep the ribbon flat, initially slack (no tension). When (not if) a tendon is severed, the secondary lines pick up the load and go into tension. This arrangement increases the net ribbon weight 20%, but greatly increases structural reliability of the ribbon. Multiple tendon breaks can be tolerated and the ribbon maintains its full strength. After a tendon failure, the fabric is locally distorted and the damage recorded by a passing cab. Every badly damaged section of ribbon must be replaced immediately.

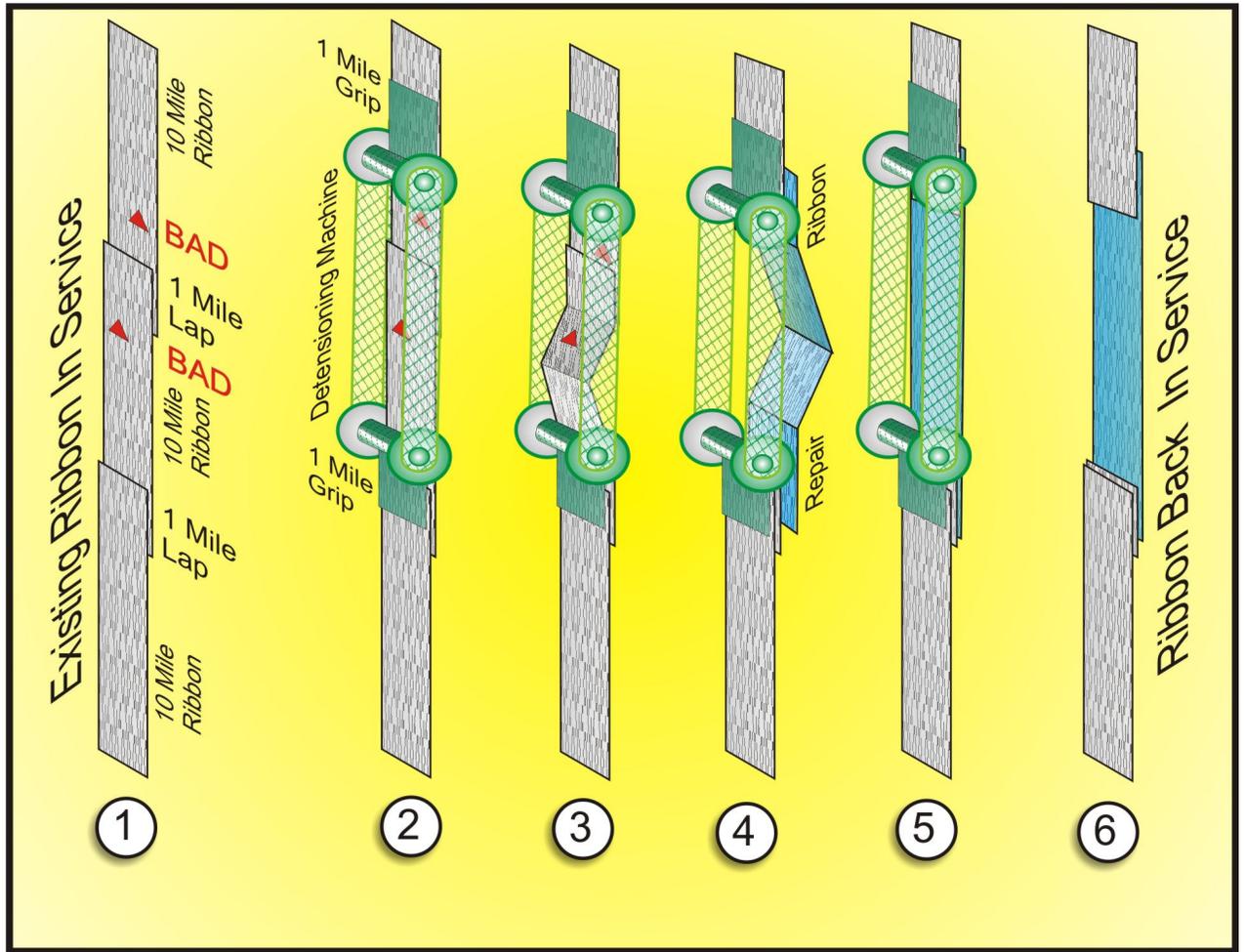
Running the ribbons through conventional drive wheels will cause excessive wear. And the cab speeds involved (2,000+ mph) cannot work with any known materials. A noncontact solution, such as a linear induction motor drive, must be developed. Another approach is to employ very thin fibers found on the toes of geckos. These *setae* fibers bond to most materials using the *Van de Walls* effect. Attached to the perimeter of a 10 foot diameter wheel spinning at 5,600 rpm, this could drive the cabs at 2,000 mph.



The ribbons will be constructed in 10 mile long strips, overlapping 1 mile at the joints. This overlap should allow the *Van de Walls Force* effect to develop the full design load of the ribbons across the splice area (See Step 1 next page). In general, this force is 1/1000<sup>th</sup> the normal ionic bonding force of the molecule.

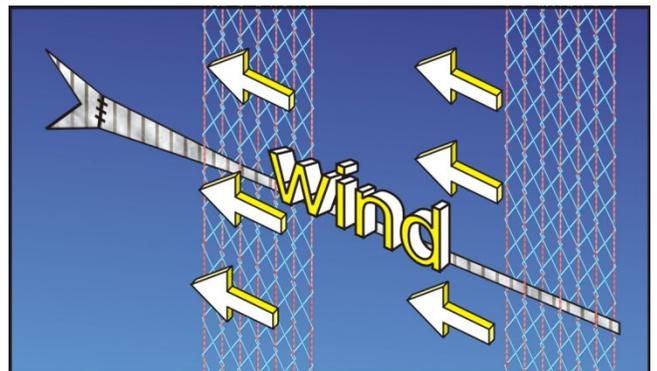
For ribbon repair, the elevator stops at the damaged section and:

- Step 2:** A *Detensioning Machine (Green)* straddles the repair area, attaching temporary 1 mile grip ribbons to the existing ribbon;
- Step 3:** The *Detensioning Machine* contracts, relieving the tension in the existing ribbon;
- Step 4:** The damaged section of ribbon is removed. The replacement ribbon (blue) is attached over the splice joint, overlapping 1 mile on each side;
- Step 5:** The *Detensioning Machine* expands, putting the new ribbon section into tension;
- Step 6:** The *Detensioning Machine* is removed, and the ribbon is back in service.



The Elevator configuration must keep the drive and climbing ribbons apart or they will tangle and/or stick to each other. The coriolis force will push the moving drive ribbon outward, but not the climbing ribbon, creating some separation. It might be necessary to positively charge the Ribbons and Cables to create a repulsive force. But this cannot interfere with the electrostatic bonding across the tether joints.

The thin ribbons will flutter in the wind, creating a vortex shedding phenomenon (remember Tacoma Narrow Bridge), and leading to premature ribbon failure. Rigid carbon fiber vanes reduce this problem, at least in moderate winds. They are computer controlled to maintain ribbon alignment and avoid twisting more than 90 degrees.

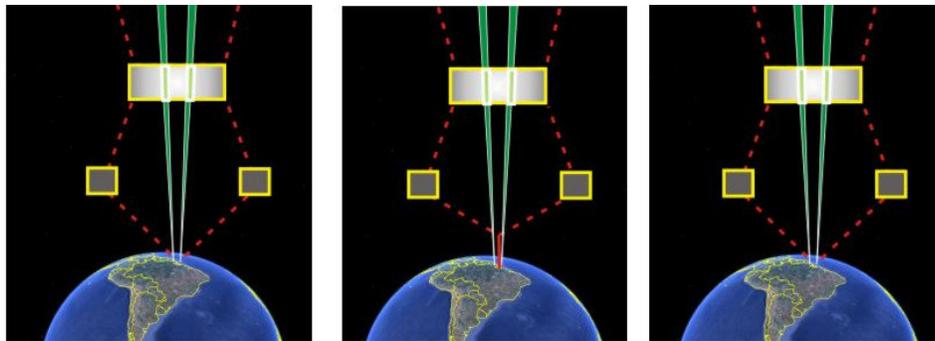


## D. Accidents and Safety

CCNTs appear to be highly toxic. Contact with CCNT fibers causes problems similar to asbestos fibers. Cell damage has been reported. Jury's still out, but this remains a problem to be resolved.

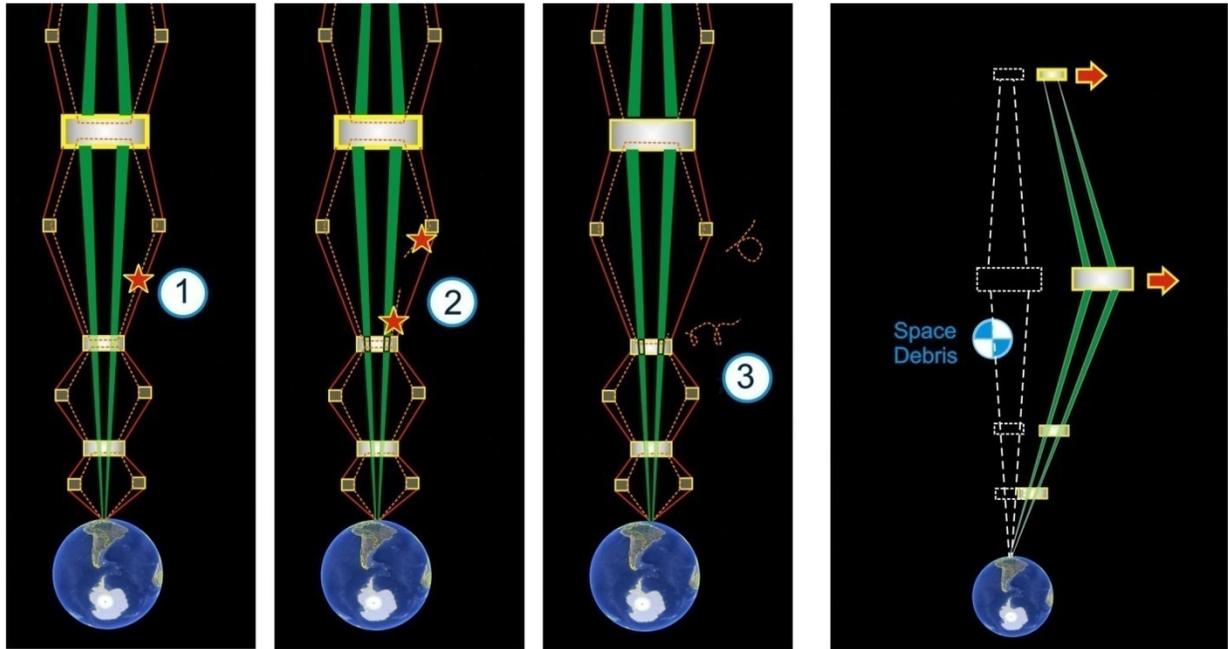
Cabs must be **Fail-Safe**: they must return to Earth safely regardless of how or where the failure occurs. When something terrible happens (and it will), the crew capsule is jettisoned, and a heat shield, parachutes, wings, and inflatable impact bags get the crew back to Earth in one piece.

Even at the best of base sites, bad weather is inevitable. For this Elevator, the lower Elevator Ribbons are held by sixteen circular tethers. These can rise up 50 miles past the stratosphere to move the ribbons out of the high winds and bad weather. Circular tethers resist dynamic wind forces better than the flat ribbons. When the bad weather passes, the ribbon supports are winched back to the ground. The Support Cable Groups, also with a circular cross-section, must also survive the high winds.



This proposed Space Elevator has four levels of elevator cabs, in sets of four at each level, and with each cab attached to eight ribbons. Eight ribbons per cab greatly reduce the risk of catastrophic failure. When a cab fails in transit, the adjacent cab is used to recover and repair the broken unit. Similarly, the Tapered Support Cables are in 16 separate bundles and spaced 500 feet apart near the ground, and 20 feet apart in space, to reduce the risk of catastrophic failure.

This Space Elevator is maneuverable. When incoming space debris or near earth objects threaten its components, the Platform and Counterweight are torqued with the drive ribbons to move the components out of harm's way. Even so, tether breakage is inevitable. The tethers are under very high tension and will immediately start contracting when broken, reaching velocities of 1,000's of miles per hour and temperatures of 1,000's °F in seconds. The ends of the snapped tethers must be immediately separated from the nearest components, allowing the pieces to contract into a ball without damaging the adjacent components. The remaining tethers are designed to take up the extra load. It would be prudent to use the Elevator for space debris control. Using simple orbital thrusters, collection spacecraft can be sent out from the Platforms to capture space debris and return it for disposal.



**E. Force Analysis**

The structural analysis of the tether forces is modeled in an interactive spreadsheet. Cab movements are based on the travel times tabulated at the right. Two cabs start up the elevator at 50 miles/hour until they clear the atmosphere. At the same time two cabs start down from the Platform, accelerating at 0.20 g’s to reach 2,000 mph. At 50 miles, the up cabs accelerate at 0.20 g’s until they also reach 2,000 mph. At 1,800 miles, they slow down and dock at Transfer Station # 1. After a 2 hour layover, the cabs start the second leg of the trip, arriving at Transfer Station # 2 eight hours after leaving home base.

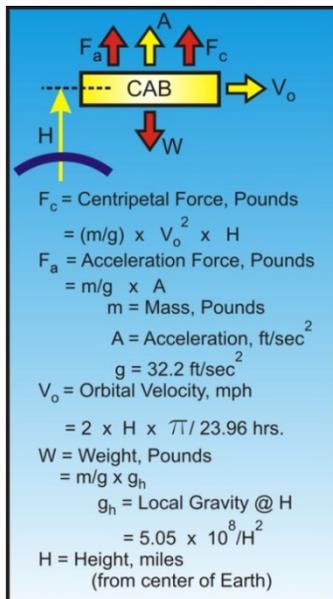
The third leg of the trip takes six hours and the cabs dock at the GS Platform 16 hours after leaving Earth.

Height Miles	Accel g	Velocity mph	Duration Hours	Elapsed Time
<b>Leave Base Station</b>				
0.00		0.00	0.00	0:00:00
0.12	0.20	50.89	0.0047	0:00:17
50		50.9	0.98	0:59:05
235	0.20	2,000.0	0.18	1:09:56
1,000		2,000.0	0.38	1:32:52
1,814		2,000.0	0.41	1:57:18
2,000	(0.20)	39.1	0.18	2:08:13
2,000	(0.05)	0.1	0.01	2:09:05
<b>Arrive Transfer Station # 1</b>			2.00	Layover
2,000				6:09:05
2,186	0.20	2,000.0	0.19	6:20:13
3,000		2,000.0	0.41	6:44:39
4,000		2,000.0	0.50	7:14:39
4,814		2,000.0	0.41	7:39:05
5,000	(0.20)	39.1	0.18	7:50:00
5,000	(0.05)	0.1	0.01	7:50:52
<b>Arrive Transfer Station # 2</b>			2.00	Layover
5,000				9:50:52
5,185	0.20	2,000.0	0.19	10:02:00
6,000		2,000.0	0.41	7:39:06
7,000		2,000.0	0.50	8:09:06
19,000		2,000.0	0.50	14:09:06
20,000		2,000.0	0.50	14:39:06
21,000		2,000.0	0.50	15:09:06
22,054		2,000.0	0.53	15:40:43
22,239	(0.20)	54.0	0.18	15:51:33
22,240	(0.05)	3.1	0.02	15:52:41
<b>Arrive GS Platform</b>			2.00	Layover

This structural analysis is a **load capacity** study of the support cables and elevator ribbons. First, tendon and ribbon forces are calculated and then compared with the allowable loads. The table at right shows the allowable loads for the various tether components.

Safety factors are applied to account for loss of strength during tether fabrication. For this study, the threads, tendons, cables and ribbons are assigned a 1.10 Safety.

Each cable tendon can support 914 pounds at a weight of 0.39 pounds per mile. A six foot wide elevator ribbon has 13 tendons and can carry 11,880 pounds at a net mass of 5.941 pounds/mile.



<b>Filament</b>		4.00 Safety Factor					
<b>extruded as pure CCNT 11 miles long</b>							
Ultimate Stress =	300 GPa			43,516 ksi	Ultimate Stress =		
				<b>10.9 M psi</b>	<b>= DESIGN STRESS</b>		
A36 Steel =	0.25 GPa			<b>36.26 ksi</b>	A36 Steel =		
Outer Diameter =	84 microns	8.40E-05 m		0.00331 inches	Outer Diameter =		
Inner Diameter =	80 microns	8.00E-05 m		0.00315 inches	Inner Diameter =		
Density =	0.116 gm/cm <sup>3</sup>			7.23 lb/CF	Density =		
Outer Area =	5,542 microns <sup>2</sup>	5.54E-09 m <sup>2</sup>		8.59E-06 in <sup>2</sup>	Outer Area =		
Inner Tube Area =	5,027 microns <sup>2</sup>	5.03E-09 m <sup>2</sup>		7.79E-06 in <sup>2</sup>	Inner Tube Area =		
Net Wall Area =	515 microns <sup>2</sup>	5.15E-10 m <sup>2</sup>		7.99E-07 in <sup>2</sup>	Net Wall Area =		
Water =	1 gm/cm <sup>3</sup>			62.33 lb/CF	OK		
<b>Allowable load = Wall Area * Allowable Stress</b>				<b>8.7 lb-f</b>	<b>Allowable load =</b>		
Unit Weight =	6.43E-04 g/m		0.00228 lb/mile	0.00228 lb/mile	Unit Weight =		
Extrude 11 miles in 4 years		production rate =		1.66 ft/hours	0.0055 in/sec		
					<b>Out. Diam. inches</b>	<b>Allow. Load Pounds</b>	<b>Weight per Mile</b>
<b>Thread</b>		1.10 Safety Factor			0.010	55.3	0.017
twisted as 7 part cable		7 filaments					
10% miles long made from 11 mile long filaments							
<b>Tendon</b>		1.10 Safety Factor			0.060	1,005	0.352
braided		20 threads					
10 mile long, made from 10% mile long threads							
					<b>Allow. Load Kips</b>	<b>Weight per Mile</b>	
<b>Elevator Ribbon # 4</b>		1.10 Safety Factor			6.40	2.461	
3 feet wide, tendons 6" oc		7 tendons					
		+20% weight for HoytRibbon + 10% overlap				3.199	
<b>Elevator Ribbon # 3</b>		1.10 Safety Factor			6.40	2.461	
3 feet wide, tendons 6" oc		7 tendons					
		+20% weight for HoytRibbon + 10% overlap				3.199	
<b>Elevator Ribbon # 2</b>		1.10 Safety Factor			11.88	4.570	
6 feet wide, tendons 6" oc		13 tendons					
		+20% weight for HoytRibbon + 10% overlap				5.941	
<b>Elevator Ribbon # 1</b>		1.10 Safety Factor			33.81	13.006	
18 feet wide, tendons 6" oc		37 tendons					
		+20% weight for HoytRibbon + 10% overlap				16.908	
					<b>Kips/mile</b>	<b>Kips/mile</b>	
<b>Cable Tendon</b>		1.10 Safety Factor		add 10% wt overlap	0.914	0.39	

A free body diagram for the elevator cab forces is shown at left. There are three forces:

Centripetal ...  $F_c$  ... = f ( $V_o, H$ )

Acceleration ....  $F_a$  .... = f (cab movement)

Weight ...  $W$  ... = f (mass, height)

The support cables, elevator ribbons, and the four platforms are also subject to centripetal and weight forces. For this structural model, the tethers are divided into 1,000 mile increments below the GS Platform, and 10,000 mile increments for tethers above the Platform.

The first set of calculations compute the orbital data and its gravity effect, as tabulated below. From here, component weight and centripetal forces are calculated. The 125,000,000 pound Counterweight weighs only 480 kips at 60,000 miles (1 kip = 1,000 pounds). Centripetal force is 6,984 Kips. The net uplift from the Counterweight is 6,504 Kips. The GS Platform is neutral since it is in geostationary orbit. Forces for each of the two Transfer Stations and the 16 elevator cabs, including cab acceleration, are also shown. The cabs are placed to maximize ribbon forces.

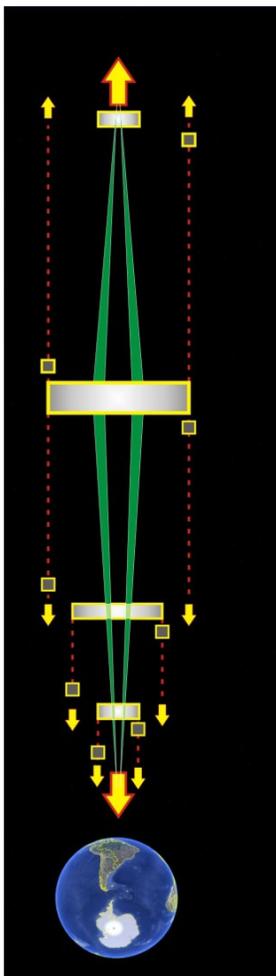
Gravity Calculations					COMPONENTS						
Altitude	C of E	Local	Local	Orbital	Altitude	Mass	Wt.	$F_c$	Accel	Accel	Net
Miles	Miles	ft/sec <sup>2</sup>	% g	mph	Miles	Kips	Kips	Kips	% g	Kips	Kips
60,000	63,963	0.12	0.4%	16,794	<b>Counterweight</b>						
55,000	58,963	0.15	0.5%	15,482	60,000	125,000	479.8	6,983.9			6,504
45,000	48,963	0.21	0.7%	12,856	<b>GS Platform</b>						
35,000	38,963	0.33	1.0%	10,230	22,240	500	11.44	11.44			0.0
25,000	28,963	0.60	1.9%	7,605	<b>Decending Cabs - in sets of two each side</b>						
22,240	26,203	0.74	2.3%	6,880	60,000	60	0.23	1.56	(0.20)	(12.00)	(13.3)
22,160	26,123	0.74	2.3%	6,859	22,000	60	1.40	1.36	(0.20)	(12.00)	(12.0)
22,000	25,963	0.75	2.3%	6,817	2,000	60	26.50	0.00	(0.20)	(12.00)	14.5
21,000	24,963	0.81	2.5%	6,554	1,000	60	38.26	0.00	(0.20)	(12.00)	26.3
20,000	23,963	0.88	2.7%	6,292	<b>Transfer Platform # 2</b>						
19,000	22,963	0.96	3.0%	6,029	5,000	100	19.55	2.19			17.4
18,000	21,963	1.05	3.3%	5,767	<b>Transfer Platform # 1</b>						
17,000	20,963	1.15	3.6%	5,504	2,000	100	44.17	1.22			42.9
16,000	19,963	1.27	3.9%	5,242	<b>Asecending Cabs - in sets of two each side</b>						
15,000	18,963	1.40	4.4%	4,979	22,240	80	1.83	1.92	0.20	16.00	15.9
14,000	17,963	1.57	4.9%	4,716	5,000	80	15.64	0.63	0.20	16.00	31.0
13,000	16,963	1.76	5.5%	4,454	2,000	80	35.34	0.42	0.20	16.00	50.9
12,000	15,963	1.98	6.2%	4,191	100	80	76.11	0.28	0.20	16.00	91.8
11,000	14,963	2.26	7.0%	3,929	<b>Data Input on Design Diagram ONLY!</b>						
10,000	13,963	2.59	8.1%	3,666	<b>(2) Distribute Counterweight Uplift Forces</b>						
9,000	12,963	3.01	9.3%	3,404	Upper Support Cables =		6,484		Kips		
8,000	11,963	3.53	11.0%	3,141	10 K each to elev. Ribbon =		10.0		Kips		
7,000	10,963	4.20	13.1%	2,879	<b>TOTAL Weight of Tethers = 146,844 Tons</b>						
6,000	9,963	5.09	15.8%	2,616							
5,000	8,963	6.29	19.5%	2,353							
4,000	7,963	7.96	24.8%	2,091							
3,000	6,963	10.42	32.4%	1,828							
2,000	5,963	14.20	44.2%	1,566							
1,000	4,963	20.50	63.8%	1,303							
100	4,063	30.59	95.1%	1,067							
0	3,963	32.15	100.0%	1,041							

**Equations**

Orbital Velocity = Orbital Circumference / (23 Hours - 56 Minutes) = 2 \* CoE Height \* pi / 23.93 hours  
 Local g = 5.05E8 / Height^2)  
 Weight = Mass \* Local g  
 Centripetal Force =  $F_c = m * v^2 / r = Mass / G * Velocity^2 / Height$  ... where Mass in pounds, Velocity in ft/sec, Height in feet  
 Tether Tension = Cumulative Centripetal Forces - Cumulative Weight + Cab Acceleration  
 Sign Convention : Tension and Forces that INCREASE tension are positive  
 Cable Mass = Segment Length in miles x Number of Tendons x Unit Weight per mile  
 Cable Weight = Cable Mass x % Local Gravity

The forces above the GS Platform are calculated first, generating a net uplift. Forces below the GS Platform are calculated next, generating a net downward force. For stability, the up forces must be larger than the down forces.

Calculations for the Elevators are shown at right. The elevator ribbon tensions for each set of cabs is first calculated hanging from the Platform and Transfer Stations as shown below.



Tether		Elevator Ribbons - 16 Up, 16 Down							
Lengths		10 Kips/Ribbon P/T							
Altitude Miles	Length Miles	Mass Kips	Wt. Kips	E <sub>c</sub> Kips	Ascending		Decending		
					Tension Kips	+ CW T.K	Tension Kips	+ CW T.K	
60,000	2,500	128.0	0.5	7.1	6.7	16.66	(6.7) (3)	3.33	
55,000	7,500	383.9	1.7	19.8	24.7	34.7	11.4	21.4	
45,000	10,000	511.8	3.4	21.9	43.2	53.2	29.9	39.9	
35,000	10,000	511.8	5.3	17.4	55.4	65.4	42.0	52.0	
25,000	6,380	326.5	6.1	8.3	57.5	67.5	44.2	54.2	
22,240	1,380	70.6	1.6	1.6	73.4 (3)	83.4	44.2	54.2	
		Total M =	1,933	Tons	Allow T =	6.4	Kips		
		W # 4, Ft. =	3		Ribbon # 4 Weight =	3.2	#/Mile		
		Allow Ribbon #4 Load =	6.4		Kips				
22,240	40	4.98	0.11	0.11	141.8	151.8	98.9	108.9	
22,160	120	14.92	0.34	0.34	141.8	151.8	98.9 (3)	108.9	
22,000	580	72.09	1.68	1.63	141.8	151.8	110.8	120.8	
21,000	1,000	124.30	3.13	2.71	141.8	151.8	110.8	120.8	
20,000	1,000	124.30	3.40	2.60	141.4	151.4	110.3	120.3	
19,000	1,000	124.30	3.70	2.49	140.6	150.6	109.6	119.6	
18,000	1,000	124.30	4.05	2.38	139.4	149.4	108.3	118.3	
17,000	1,000	124.30	4.44	2.28	137.7	147.7	106.7	116.7	
16,000	1,000	124.30	4.90	2.17	135.5	145.5	104.5	114.5	
15,000	1,000	124.30	5.43	2.06	132.8	142.8	101.8	111.8	
14,000	1,000	124.30	6.05	1.95	129.4	139.4	98.4	108.4	
13,000	1,000	124.30	6.78	1.84	125.3	135.3	94.3	104.3	
12,000	1,000	124.30	7.66	1.73	120.4	130.4	89.4	99.4	
11,000	1,000	124.30	8.72	1.62	114.5	124.5	83.4	93.4	
10,000	1,000	124.30	10.01	1.52	107.4	117.4	76.3	86.3	
9,000	1,000	124.30	11.62	1.41	98.9	108.9	67.9	77.9	
8,000	1,000	124.30	13.64	1.30	88.7	98.7	57.6	67.6	
7,000	1,000	124.30	16.24	1.19	76.3	86.3	45.3	55.3	
6,000	1,000	124.30	19.67	1.08	61.3	71.3	30.2	40.2	
5,000	500	62.15	12.15	0.49	42.7 (3)	52.7	11.7	21.7	
5,000	500	91.39	17.87	0.72	210.1	220.1	159.1 (3)	169.1	
4,000	1,000	182.79	45.27	1.27	192.9	202.9	142.0	152.0	
3,000	1,000	182.79	59.21	1.11	148.9	158.9	98.0	108.0	
2,000	500	91.39	40.37	0.48	90.8 (3)	100.8	39.9	49.9	
2,000	500	266.87	117.88	1.39	809.0	819.0	731.6 (3)	741.6	
1,000	950	507.06	323.31	2.20	692.5	702.5	600.7	610.7	
100	500	266.87	253.90	0.95	371.4 (3)	381.4	279.5	289.5	
0	50	26.69	26.69	0.09	26.6	36.6	26.6	36.6	
		Total M =	1,879	Tons					
		# 3 W ft =	8	Ribbon # 3 #/mi =	7.8	All. Load K =	15.5		
		# 2 W ft =	12	Ribbon # 2 #/mi =	11.4	All. Load K =	22.8		
		# 1 W Ft =	36	Ribbon # 1 #/mi =	33.4	All. Load K =	66.7		
3) Add Cab Forces to Ribbon Tension									
Stability Check before Post Tensioning (P/T)									
Total Weight below GS Platform =		11,178	Total Weight above GS Platform =		2,492				
Acceleration =		12.00	Net Acceleration =		4.00				
Total Cent. Force below GS Platform =		1,462	Total Cent. Force above GS Platform =		14,465				
NET =		9,728	NET =		11,977				
Cable + Ribbon Tensions =		9,842	Cable + Ribbon Tensions =		11,975				

There are 4 drive and 4 climbing ribbons for each of two cabs. They are combined and analyzed as a single force (i.e. 16 ribbons are treated as one tether for each set of two cabs). The up and down ribbons are computed separately. Next, the ribbons are attached to a lower structure and a tension of 10 kips added to each set of ribbons to stabilize it.

The next step is to normalize the belt forces so they sum to zero around each drive loop. The diagram at right lays out the process. At the Counterweight, the upper Loop Ribbon # 4 passes through a Genset to produce station power. With a 5 kip ribbon load moving at 10 mph:

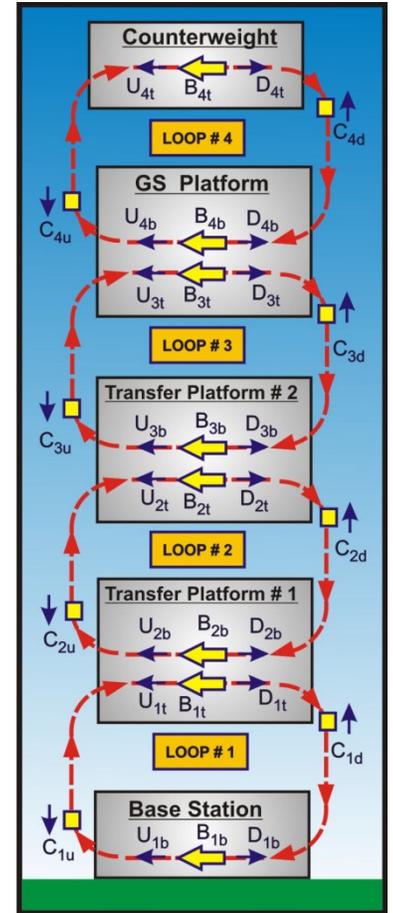
$$\begin{aligned}
 \text{Power} &= 5 \text{ Kips} \times 14.67 \text{ ft/sec} \\
 &= 73,350 \text{ ft-lbs/second} \\
 &= 133 \text{ HP} = 75 \text{ KW (75\% efficiency)}
 \end{aligned}$$

This 5 Kip load across the genset is designated Load  $B_{4t}$ . The upper left ribbon tension  $U_{4t}$  plus  $B_{4t}$  must equal the upper right tension  $D_{4t}$ . From the initial ribbon calcs:

$$\begin{aligned}
 U_{4t} + B_{4t} &= D_{4t} \\
 16.66 \text{ K} + 5.0 \text{ K} &= 3.33 \quad \text{Delta} = 18.33 \text{ Kips}
 \end{aligned}$$

Half this tension imbalance is added to the right ribbon, and half released from the left ribbon:

$$\begin{aligned}
 (16.66 \text{ K} - 9.17 \text{ K}) + 5.0 \text{ K} &= (3.33 + 9.17 \text{ K}) \\
 7.49 \text{ K} + 5.0 \text{ K} &= 12.49 \text{ K} \quad \dots \text{ and Delta} = 0 \text{ Kips}
 \end{aligned}$$



The lower end of Loop #4 passes through the GS Platform. The belt force here,  $B_{4b}$ , must drive the upper genset, Load  $B_{4t}$ , and also move the two cabs. Cab  $C_{4u}$  must be pulled up by the ribbons, while Cab  $C_{4d}$  acts like a typical elevator counterweight, helping to pull the other Cab up. Belt force  $B_{4b}$  is computed as 7.58 Kips as tabulated at right. The imbalance here is 36.81 Kips and again normalized 50/50.

This causes the drive ribbon to become too slack, and an additional 10 Kips is added to both sides to stabilize the ribbons. Loop # 1 requires 50 Kips extra tension to stabilize it.

The remaining belt calcs are also shown in this table. A 500 KW genset is provided at the GS Platform, and 75 KW gensets power the Transfer Stations. At the Base Station, the winches that power the loop drive ribbons deliver 123 Kips ( $B_{1b}$ ) of thrust to power the entire Elevator.

Force	Initial Delta	Adjust Tension
<b>B4u =</b> 5 Kips	18.33	
5 = 75 KW genset		10
<b>B4d =</b> 7.58 Kips	36.81	
5 = B4u		
2.6 = C4u-C4d		
<b>B3u =</b> 57.58 Kips	100.55	
7.58 = B4d		20
50 = 500 KW genset		
<b>B3d =</b> 76.63 Kips	107.64	
57.58 = B3u		
19.1 = C3u-C3d		
<b>B2u =</b> 81.63 Kips	132.55	
76.63 = B3d		
5 = 75 KW genset		0
<b>B2d =</b> 118.05 Kips	168.96	
81.63 = B2u		
36.4 = C2u-C2d		
<b>B1u =</b> 123.05 Kips	200.37	
118.05 = B2d		
5 = 75 KW genset		50
<b>B1d =</b> 123.05 Kips	123.05	
123.05 = B1u		
65.6 = C1u-C1d		

The normalized Drive Ribbon tensions are shown at right. Peak tension is 892 Kips just below Transfer Platform # 1 on the down side of Loop # 1. Drive loop # 4 has the lowest tension at 17 Kips.

These disproportionate ribbon forces are not sound engineering, and a more balanced load between the three lower drive loops is clearly preferable. This would allow a single width ribbon for these three drive loops, simplifying construction and maintenance.

Several alternative configurations were examined:

- 1) Add a third Transfer Station @ 750 miles;
- 2) Lower the two Transfer Stations to 4,000 and 750 miles.

Both of these schemes are preferable to the one studied here, and a combination of the two is probably the best solution. However, this study is not intended to produce an optimized Elevator design. Its primary purpose is to demonstrate that a looped drive belt can power the Elevator. The next engineering study (assuming there is one?) should begin with a detailed assessment of the operational parameters of the Elevator. This could establish where the best platform locations should be for completing space missions.

*(But the HCG Space Elevator is intended as the second step in a broader vision of the conquest of space. The major lift required for this elevator is for proposed Step # 3: launching the 25,000,000 pound HCG Space Ship 1:*

<http://www.hicon.us/gpage28.html>

*And mankind will be able to travel between the stars!)*

<b>Normalize Loop Tension</b>				
	Normalize Ascending	Normalize Descending	Final	
Altitude	Cable	Cable	Delta	
Miles	Tension	Tension	Tension	Check
60,000	17.49	22.49	5.00	B4u
55,000	34.31	41.75		
45,000	50.40	62.74		
35,000	60.07	77.31		
25,000	59.77	81.90		
22,240	75.00	82.58	7.58	B4d
22,240	121.56	179.13	57.58	B3u
22,160	121.54	179.15		
22,000	121.50	191.14		
21,000	121.25	191.30		
20,000	120.63	191.09		
19,000	119.62	190.49		
18,000	118.21	189.49		
17,000	116.34	188.03		
16,000	113.97	186.07		
15,000	111.03	183.55		
14,000	107.46	180.38		
13,000	103.15	176.49		
12,000	98.00	171.75		
11,000	91.87	166.03		
10,000	84.57	159.14		
9,000	75.87	150.85		
8,000	65.45	140.85		
7,000	52.90	128.71		
6,000	37.65	113.86		
5,000	18.86	95.48	76.63	B3d
5,000	153.79	235.42	81.63	B2u
4,000	130.57	224.34		
3,000	80.50	186.40		
2,000	16.33	134.37	118.05	B2d
2,000	768.78	891.83	123.05	B1u
1,000	671.63	741.51		
100	367.92	403.00		
0	25.07	148.12	123.05	B1d

1) All forces in Kips (= 1,000 pounds)

With the normalized loads for the ribbon loops computed, their safety is next evaluated (see below). The tensions in normalization table are increased 5% for the right side (the pulling side) and 2½% on the left side to allow for friction losses. To determine the actual force for each ribbon, these tensions are divided by 16. One of the cab ribbons is severed and the safety for of the remaining 7 ribbons computed. This provides an additional safety factor when (not if) one of the elevator ribbons is severed. By adjusting the ribbon width, a stable elevator system is designed. Loop # 1 is 36 feet wide, Loop # 2 is 12 ft., # 3 8 ft., and # 4 is 3 feet wide.

Design Elevator Ribbon									
<b>Up Cabs - 16 Ribbons</b>					<b>Down Cabs - 16 Ribbons</b>				
Altitude Miles	Total Tension	Ribbon	Safety		Total Tension	Ribbon	Safety		
60,000	Kips	Tension	Factor	OK?	Kips	Each-K	Factor	OK?	
60,000	17.93	1.12	5.02		23.62	1.48	3.81		
55,000	35.16	2.20	2.56		43.84	2.74	2.05		
45,000	51.66	3.23	1.74		65.87	4.12	1.37		
35,000	61.57	3.85	1.46		81.17	5.07	1.11		
25,000	61.27	3.83	1.47		86.00	5.37	1.05		
22,240	76.88	4.80	1.17		86.71	5.42	1.04		
22,240	<b>Up Cabs - 16 Ribbons</b>				<b>Down Cabs - 16 Ribbons</b>				
22,240	124.6	7.8	1.8		188.1	11.8	1.2		
22,160	124.6	7.8	1.8		188.1	11.8	1.2		
22,000	124.5	7.8	1.8		200.7	12.5	1.1		
21,000	124.3	7.8	1.8		200.9	12.6	1.1		
20,000	123.6	7.7	1.8		200.6	12.5	1.1		
19,000	122.6	7.7	1.8		200.0	12.5	1.1		
18,000	121.2	7.6	1.8		199.0	12.4	1.1		
17,000	119.2	7.5	1.8		197.4	12.3	1.1		
16,000	116.8	7.3	1.9		195.4	12.2	1.1		
15,000	113.8	7.1	1.9		192.7	12.0	1.1		
14,000	110.1	6.9	2.0		189.4	11.8	1.2		
13,000	105.7	6.6	2.1		185.3	11.6	1.2		
12,000	100.5	6.3	2.2		180.3	11.3	1.2		
11,000	94.2	5.9	2.3		174.3	10.9	1.3		
10,000	86.7	5.4	2.5		167.1	10.4	1.3		
9,000	77.8	4.9	2.8		158.4	9.9	1.4		
8,000	67.1	4.2	3.3		147.9	9.2	1.5		
7,000	54.2	3.4	4.0		135.1	8.4	1.6		
6,000	38.6	2.4	5.7		119.6	7.5	1.8		
5,000	19.3	1.2	11.3		100.3	6.3	2.2		
5,000	-	-	-		-	-	-		
5,000	157.6	9.9	2.0		247.2	15.4	1.1		
4,000	133.8	8.4	2.4		235.6	14.7	1.2		
3,000	82.5	5.2	3.9		195.7	12.2	1.4		
2,000	16.7	1.0	19.2		141.1	8.8	1.9		
2,000	-	-	-		-	-	-		
2,000	788.0	49.3	1.2		936.4	58.5	1.0		
1,000	688.4	43.0	1.4		778.6	48.7	1.2		
100	377.1	23.6	2.5		423.2	26.4	2.2		
0	25.7	1.6	36.5		155.5	9.7	6.0		
<b>Earth</b>									
<b>Notes:</b> For loop friction losses, 2½% tension added to all Up ribbons and 5% added to all Down ribbons									
Elevator Safety Factor Based on 7 of 8 Cab Ribbons still OK (1 broken each cab) $SF = 0.88 * T_{Allow} / T_{calcd}$									
1. Two 30,000 # Cabs Accel. Down @ 0.2 g's									
2. Two 40,000 # Cabs Accel. Up @ 0.2 g's									
Ribbon #4 Width, Ft. = 3					Allow. Load/Ribbon, Kips = 6.40				
Ribbon #3 Width, Ft. = 8					Allow. Load/Ribbon, Kips = 15.54				
Ribbon #2 Width, Ft. = 12					Allow. Load/Ribbon, Kips = 22.85				
Ribbon #1 Width, Ft. = 36					Allow. Load/Ribbon, Kips = 66.71				

The tension loads on the Tapered Support Cables are designed next (see table at right). Loads are summed from the Counterweight down to the GS Platform. The Upper Cable has a tension of 11,857 Kips at the GS Platform, decreasing to 6,957 Kips at the Counterweight. The Upper Cable tapers from 15,500 tendons at the Counterweight to 9,000 at the GS Platform.

The Support Cable tension below the GS Platform is summed from the ground up. The loads from the Transfer Stations and the attached elevator ribbons # 1 and # 2 are added at 2,000 and 5,000 miles. The 1,064 Kip uplift from the Upper Support cable is then added as a post-tensioning load. The Lower Support Cable carries 1,736 Kips at the ground and 10,644 Kips at the GS Platform. The number of tendons taper from 1,900 at the Base Station to 13,700 at the GS Platform. Uplift at the ground and at the GS Platform are both over 1,000 Kips, providing a reasonable tension to keep the Elevator stable.

The table on the next page evaluates the safety of the support cables. This is a five step iterative process:

- 1) Size the CW;
- 2) Size the Upper Cable;
- 3) Size the Lower Cable;
- 4) Check Uplift;
- 5) Go back to Step # 1 until stable.

<u>Tether</u>		<u>Support Cables - Tapered Tendons</u>						
<u>Lengths</u>		Carries Counterweight Uplift Load - Elevator P/T						
<u>Altitude</u>	<u>Length</u>	<u>#</u>	<u>Mass</u>	<u>Wt.</u>	<u>E<sub>c</sub></u>	<u>T</u>	<u>T-Allow</u>	
<u>Miles</u>	<u>Miles</u>	<u>Tendons</u>	<u>Kips</u>	<u>Kips</u>	<u>Kips</u>	<u>Kips</u>	<u>Kips</u>	
60,000	2,500	9,000	8,700	33.4	486.1	6,957 (2)	8,224	
55,000	7,500	11,000	31,900	144.1	1,643.0	8,456	10,052	
45,000	10,000	13,000	50,267	329.3	2,149.9	10,276	11,880	
35,000	10,000	14,600	56,454	584.0	1,921.3	11,614	13,342	
25,000	6,380	15,000	37,004	692.8	936.2	11,857	13,707	
22,240	1,380	15,500	8,271	189.2	189.3	11,857	14,164	
						<u>T +</u>		
		<u>#</u>	<u>Mass</u>	<u>Wt.</u>	<u>E<sub>c</sub></u>	<u>T</u>	<u>Uplift</u>	<u>T-Allow</u>
		<u>Tendons</u>	<u>Kips</u>	<u>Kips</u>	<u>Kips</u>	<u>Kips</u>	<u>Kips</u>	<u>Kips</u>
22,240	40	13,700	212	4.9	4.86	9,601	10,644	12,519
22,160	120	13,700	636	14.6	14.5	9,601	10,644	12,519
22,000	580	13,633	3,058	71.2	69.3	9,601	10,644	12,459
21,000	1,000	13,567	5,246	132.2	114.4	9,599	10,642	12,398
20,000	1,000	13,500	5,220	142.8	109.3	9,581	10,625	12,337
19,000	1,000	13,460	5,205	155.0	104.4	9,548	10,591	12,300
18,000	1,000	13,420	5,189	168.9	99.6	9,497	10,540	12,264
17,000	1,000	13,380	5,174	184.9	94.7	9,427	10,471	12,227
16,000	1,000	13,340	5,158	203.3	89.9	9,337	10,381	12,191
15,000	1,000	13,300	5,143	224.6	85.2	9,224	10,267	12,154
14,000	1,000	13,040	5,042	245.4	79.1	9,085	10,128	11,916
13,000	1,000	12,780	4,942	269.7	73.2	8,918	9,962	11,679
12,000	1,000	12,520	4,841	298.4	67.5	8,722	9,765	11,441
11,000	1,000	12,260	4,741	332.5	62.0	8,491	9,534	11,204
10,000	1,000	12,000	4,640	373.8	56.6	8,220	9,264	10,966
9,000	1,000	12,120	4,686	438.0	53.1	7,903	8,947	11,076
8,000	1,000	11,360	4,393	482.0	45.9	7,518	8,562	10,381
7,000	1,000	10,600	4,099	535.6	39.2	7,082	8,126	9,687
6,000	1,000	9,840	3,805	602.0	33.1	6,586	7,629	8,992
5,000	500	9,300	1,798	351.5	14.1	6,017 (1)	7,060	8,499
5,000	500	8,200	1,585	309.9	12.4	5,273	6,316	7,493
4,000	1,000	8,100	3,132	775.7	21.79	4,975	6,019	7,402
3,000	1,000	6,840	2,645	856.7	16.09	4,221	5,265	6,251
2,000	500	3,700	715	316.0	3.73	3,381 (1)	4,424	3,381
2,000	500	3,700	715	316.0	3.73	1,365	2,408	3,381
1,000	950	2,800	1,029	655.8	4.46	1,053	2,096	2,559
100	500	1,990	384.7	366.0	1.37	401	1,445	1,819
0	50	1,900	36.7	36.73	0.13	37	1,080	1,736
		<b>Total M = 143,032 Tons</b>						
		<b>Weight per Tendon =</b>					<b>0.39 Pounds/Mile</b>	
		<b>Allowable Tendon Load =</b>					<b>0.914 Kips/Tendon</b>	
		<b>1) Add Transfer Station + Normalized Lower Elevator Ribbon Forces here</b>						
		<b>NET UPLIFT @ GS PLATFORM =</b>					<b>1,064 Kips</b>	
		<b>Distribute Net Uplift Forces</b>						
		<b>@ GS Platform to Lower Tethers</b>						
		Apply to Lower Support Cable =					1,043.5 Kips	
		10 Kips to each lower & middle elev. Ribbon =					10.0 Kips	

The tendon safety factor is based on fourteen of sixteen cable groups in service: one is assumed severed and a second one is under repair.

Design Support Cables									
Altitude Miles						Tension		Safety Factor	OK?
						Total Tension Kips	per ea. Tendon Kips		
60,000		Wt, Kips =	125,000		<b>Counterweight</b>				
60,000		# Upper Loop Tendons =	9,000			6,957	0.77	1.03	
55,000		# Upper Loop Tendons =	11,000			8,456	0.77	1.04	
45,000		# Upper Loop Tendons =	13,000			10,276	0.79	1.01	
35,000		# Upper Loop Tendons =	14,600			11,614	0.80	1.01	
25,000		# Upper Loop Tendons =	15,000			11,857	0.79	1.01	
22,240		# Upper Loop Tendons =	15,500			11,857	0.76	1.05	
22,240	<b>Uplift</b>	Kips	<b>OK</b>		<b>GS Platform</b>				
22,240			13,700			10,644	0.78	1.03	
22,160		# Support Tendons =	13,700			10,644	0.78	1.03	
22,000			13,633			10,644	0.78	1.02	
21,000			13,567			10,642	0.78	1.02	
20,000		# Support Tendons =	13,500			10,625	0.79	1.02	
19,000			13,460			10,591	0.79	1.02	
18,000			13,420			10,540	0.79	1.02	
17,000			13,380			10,471	0.78	1.02	
16,000			13,340			10,381	0.78	1.03	
15,000		# Support Tendons =	13,300			10,267	0.77	1.04	
14,000			13,040			10,128	0.78	1.03	
13,000			12,780			9,962	0.78	1.03	
12,000			12,520			9,765	0.78	1.03	
11,000			12,260			9,534	0.78	1.03	
10,000		# Support Tendons =	12,000			9,264	0.77	1.04	
9,000			12,120			8,947	0.74	1.08	
8,000			11,360			8,562	0.75	1.06	
7,000			10,600			8,126	0.77	1.04	
6,000			9,840			7,629	0.78	1.03	
5,000		# Support Tendons =	9,300			7,060	0.76	1.05	
5,000					<b>Trans. Station # 2</b>				
5,000		# Support Tendons =	8,200			6,316	0.77	1.04	
4,000			8,100			6,019	0.74	1.08	
3,000			6,840			5,265	0.77	1.04	
2,000		# Support Tendons =	6,500			4,424	0.68	1.17	
2,000					<b>Trans. Station # 1</b>				
2,000		# Support Tendons =	3,700			2,408	0.65	1.23	
1,000			2,800			2,096	0.75	1.07	
100			1,990			1,445	0.73	1.10	
0		# Support Tendons =	1,900			1,080	0.57	1.41	
<b>Earth</b>									
						<b>NOTE : Tendon Safety Factor Based on</b>			
						2 of 16 cable bundles out of service			
						SF = (14/16) * (T <sub>Allow</sub> ) / (T <sub>calcd</sub> )			
<b>Above Platform, Kips =</b>		12,020.6	<b>UPLIFT</b>						
<b>NET UPLIFT, KIPS =</b>		1,063.5	1,063.5						
<b>Below Platform, Kips =</b>		10,957.05	Circular Reference Problem		<b>Adjustable Cells =</b>				
<b>At Ground, Kips =</b>		1,261.33	Must manually INPUT Uplift		<b>Allow. Tendon Tension, Kips =</b>		0.91		

## F. Costs

The bottom line is **MONEY**: the cost to send one pound of payload into GS orbit. Chemical rockets generally run \$ 20,000/pound and are notoriously unreliable. There are many other launch proposals on the drawing boards, but only the proposed *HCG ICC-1 Launch Vehicle* (<http://www.hicon.us/gpage26.html>) can launch a GS payload for less than \$ 3,000 a pound with a 99+% reliability.

The first step is to build a Base Station on a 100 acre site, with a 100,000 square foot Operations Building and a 10 MW power plant. Next step is to build a 1/100<sup>th</sup> size *Construction Elevator*. Hopefully, it can be done for 1/4<sup>th</sup> the cost of the final unit. Estimated weight is 1,300,000 pounds. Gradually, this small elevator will be expanded into the big one.

The major cost item for the *HCG Space Elevator* is the lift costs: \$ 3.8 B for the temporary elevator and \$ 22 B for the final. The next most expensive item is the CCNT tethers: \$ 3.7 B. Hopefully they will cost only \$ 100/pound to manufacture in 2020. The 2009 price of carbon fiber is \$ 10/pound.

The budget for the proposed *HCG Space Elevator* is on the next page. Construction cost is estimated at \$ 41 B, with annual operating costs estimated at \$ 4.5 B/year. The eight cabs can lift 142,000 pounds a day and 52,000,000 pounds per year into Orbit at an estimated cost of around \$ 100 per pound. That's a lot of satellites and at least one Star Ship every year!

## G. Conclusions

We can build this by 2025. We must build this, or something similar, for the very survival of our species. With this *HCG Space Elevator*, we will have the ability to orbit 52 Million pounds/year for only \$ 100 per pound. And *Homo Sapiens* will be on the way to the conquest of space. "*The final frontier.*"

The *Proposed HCG Space Elevator* presented in this report will not resemble the first **Space Elevator** actually built. It is intended to show feasibility, establish realistic budget costs, and to encourage the World to immediately fund the research needed to get things started.

**References:** (*Note: Data in this report came off these web sites and the links provided*)

[http://en.wikipedia.org/wiki/Space\\_elevator](http://en.wikipedia.org/wiki/Space_elevator) ..... A good starting point.

[http://en.wikipedia.org/wiki/Carbon\\_nanotube](http://en.wikipedia.org/wiki/Carbon_nanotube) ..... Background on CNT's.

[http://en.wikipedia.org/wiki/Colossal\\_carbon\\_tube](http://en.wikipedia.org/wiki/Colossal_carbon_tube) ..... Background on CCNT's.

<http://www.mse.ncsu.edu/research/zhu/papers/CNT/PRL-CCTs.pdf> ..... Peng's Paper

<http://www.spaceelevatorblog.com/> ..... up-to-date web blog

<b>HCG's Space Elevator Budget</b>						
<u>Item</u>	<u>Quantity</u>	<u>Units</u>	<u>Unit Cost</u>	<u>Total Cost</u>	<u>Comments</u>	
<b>Base Site</b>						
Land + Sitework	100	Acres	\$ 250,000	\$ 25,000,000		
Building	100,000	SF	\$ 400	\$ 40,000,000		
Power Plant	10	MegaWatts	\$ 2,500,000	\$ 25,000,000	HeliTubes, HeliWinds	
Drive Winches	4	each	\$ 500,000	\$ 2,000,000	2,500 HP	
Equip., Spare Parts		LS		\$ 10,000,000		
				<b>Subtotal = \$</b>	<b>102,000,000</b>	
<b>Space Elevator</b>						
<b>Build out from Temporary Elevator</b>						
Tethers	146,844	Tons	\$ 20,000	\$ 2,936,884,284	\$ 100/lb	
Transfer Station	200,000	lbs	\$ 750	\$ 150,000,000	Two	
GS Platform	500,000	lbs	\$ 750	\$ 375,000,000		
Counterweight	125,000,000	lbs	\$ 25	\$ 3,125,000,000		
Lift into Space	125,846,844		\$ 175	\$ 22,023,197,737	Using Tempory Elevator	
Elevator Cabs	20	each	\$ 2,500,000	\$ 50,000,000	4 spares	
Emergency Lift Cables	16	each	\$ 1,000,000	\$ 16,000,000	to avoid bad weather	
Detension Machine	2	each	\$ 10,000,000	\$ 20,000,000		
Spare Tethers	36,711	Tons	\$ 20,000	\$ 734,221,071	Replace 1/4 per year	
				<b>Subtotal = \$</b>	<b>29,430,303,093</b>	
<b>Temporary Elevator</b>						
<b>1/100 the capacity of the final</b>						
Build	1,258,468	lbs		\$ 7,383,075,773	i.e. 200# cab capacity to start	
Lauch into Orbit	1,258,468	lbs	\$ 3,000	\$ 3,775,405,326	<b>1/4 the cost of the final</b>	
				<b>\$</b>	<b>11,158,481,100</b>	<b>Use ICC-1 Launch Vehicle</b>
				<b>TOTAL = \$</b>	<b>40,690,784,192</b>	
<b>Annual Costs</b>						
Staff	500	people	\$ 200,000	\$ 100,000,000		
O&M		LS		\$ 100,000,000		
Replace Tethers & Cables		LS		\$ 734,221,071	25% each year	
Cap Loan				\$4,144,000,000	8%, 20 years	
				<b>TOTAL = \$</b>	<b>5,078,221,071</b>	per year
<b>Payload Orbit Costs</b>						
18 Hours/trip x 8 cabs x 20,000#/trip * 67% up time =						
142,933 #/day 52,206,400 #/year						
			<b>COST =</b>	<b>\$ 97.00</b>	<b>per pound</b>	